Referências

[1] Zvi Artstein. Examples of stabilization with hybrid feedback. In R Alur, TA Henzinger, and ED Sontag, editors, *Hybrid System III*, volume 1066 of *Lect. Notes Comp. Sci.*, chapter 13, pages 173–185. Springer Verlag, Berlin, 1996.

[2] K. J. Åström and B. Wittenmark. *Adaptive Control.* Addison-Wesley, 1989.

[3] S Bennett. *A history of control engineering, 1800-1930.* Peter Peregrinus / IEE, London, 1979.

[4] S Bennett. *A history of control engineering, 1930-1955.* Peter Peregrinus / IEE, London, 1993.

[5] Michael S Branicky. *Studies in Hybrid Systems: Modelling, Analysis, and Control.* PhD thesis, Massachussetts Institute of Technology, June 1995.

[6] Wen-Chung Chang, AS Morse, and Gregory D Hager. A calibration-free, self-adjusting stereo visual control system. In *13th World Congress*, pages 343–348, San Francisco, July 1996. IFAC.

[7] Simon Haykin. *Adaptive filter theory.* Prentice Hall, Englewood Cliffs, 3 edition, 1997.

[8] Pablo E Jojoa, Max Gerken, and Felipe M Pait. Um algoritmo acelerador de parâmetros. In XVI *Simpósio Brasileiro de Telecomunicações*, Vitória, —textsces, setembro 1999.

[9] Donald E Knuth. *Selected papers in computer science.* Cambridge University Press, 1996.

[10] Ilya Kolmanovsky and N Harris McClamroch. Developments in nonholonomic control problems. *IEEE Control Systems Magazine*, pages 20–36, December 1995.

[11] Iven Mareels and Jan Willem Polderman. *Adaptive Systems: An Introduction.* Birkhäuser, Boston, 1996.

[12] O Mayr. *Zur Frügeschichte der Technischen Regelungen.* Oldenbourg, München, 1969. (English translation: The origins of feedback control, MIT Press, Cambridge, Mass., 1970).

[13] A Stephen Morse and Felipe M Pait. MIMO design models and internal regulators for cyclically-switched parameter-adaptive control systems. IEEE *Trans. Automatic Control*, 39(9):1809–1818, September 1994.

[14] Felipe M Pait. *Elementos de controle adaptativo.* Universidade de São Paulo, 1998. (tese de livre-docência).

[15] Felipe M Pait. A tuner that accelerates parameters. *Systems & Control Letters*, 35(1):65–68, August 1998.

[16] Felipe M Pait and Fuad Kassab Jr. *Parallel algorithms for adaptive control: Robust stability*, volume Control Using Logic-Based Switching of *Lecture Notes in Control and Information Sciences, 222*, pages 262–276. Springer Verlag, 1996.

[17] Felipe M Pait and Fuad Kassab Jr. On a class of switched, robustly stable, adaptive systems. In *Conference on Decision and Control*, Phoenix, Arizona, December 1999.

[18] Felipe M Pait and A Stephen Morse. Global tunability of one-dimensional siso systems. IEEE *Trans. Automatic Control*, 37(10):1605–1608, October 1992.

[19] Felipe M Pait and A Stephen Morse. A cyclic switching strategy for parameter adaptive control. IEEE *Trans. Automatic Control*, 39(6):1172–1183, June 1994.

[20] Benedetto Piccoli, Felipe M Pait, and Anselmo Bittar. A hybrid controller for a nonholonomic system. *Controle & Automação*, 9(2):85–89, maio 1998.

[21] Ali Hussein Sayed, Thomas Kailath, and Babak Hassibi. *Indefinite Quadratic Estimation and Control: A Unified Approach to $\mathcal{H}_2$ and $\mathcal{H}_\infty$ Theories.* SIAM, Philadelphia, 1999.